# General form of M-probabilities on IF-events

Beloslav Riečan

Faculty of Natural Sciences, Matej Bel University Department of Mathematics Tajovského 40 974 01 Banská Bystrica, Slovakia and Mathematical Institute of Slovak Acad. of Sciences Štefánikova 49 SK–81473 Bratislava riecan@fpv.umb.sk

#### Abstract

In M-probability theory the additivity is considered with respect to the Gödel operations (maximum, minimum). The representation theorem is proved under the assumption that the M-probability depends on the integrals of the membership function and the nonmembership function.

**Keywords:** IF-events, t-norms, probability.

### 1 IF-events

Consider a classical probability space  $(\Omega, \mathcal{S}, P)$ . An IF-event is a pair  $A = (\mu_A, \nu_A)$  of  $\mathcal{S}$ -measurable real functions  $\mu_A, \nu_A : \Omega \to [0, 1]$  such that

$$\mu_A + \nu_A \le 1.$$

There is a very suitable terminology:  $\mu_A$  is called the membership function,  $\nu_A$  the nonmembership function. If  $f: \Omega \to [0,1]$  is an S-measurable fuzzy set, then the pair (f, 1-f)is an IF-event, of course IF-events present a larger family.

Denote by  $\mathcal{F}$  the family of all IF-events. There are many possibilities how to define a state  $m : \mathcal{F} \to [0, 1]$ . First in [3 - 5] the additivity was studied with respect to Lukasiewicz connectives. In [4] general form of states (with respect to the connectives) was presented and in [5] the theory was imbedded to the MValgebra probability theory [7]. Of course, in [2] the Gödel connectives were introduced instead of Lukasiewicz ones. Some basic results in M-probability theory (using the Gödel connectives) has been summarized in [1] and [6]. In this communication we present a general form of M-states.

The Gödel connectives are defined in the following way:

$$A \lor B = (\mu_A \lor \mu_B, \nu_A \land \nu_B),$$
  
$$A \land B = (\mu_A \land \mu_B, \nu_A \lor \nu_B),$$

where

$$f \lor g = \max(f, g), f \land g = \min(f, g)$$

Recall that

$$A \leq B \iff \mu_A \leq \mu_B, \nu_A \geq \nu_B.$$

An additive *M*-state is a mapping  $m : \mathcal{F} \to [0, 1]$  such that

- (i) m((0,1)) = 0, m((1,0)) = 1,
- (ii)  $m(A) + m(B) = m(A \lor B) + m(A \land B)$ for any  $A, B \in \mathcal{F}$ .

An additive M-state is called an M-state, if it is continuous, i.e.

(iii)  $A_n \nearrow A, B_n \searrow B \Longrightarrow$  $m(A_n) \nearrow m(A), m(B_n) \searrow m(B).$ 

#### 2 Representation theorem

**Theorem.** Let  $m : \mathcal{F} \to [0, 1]$  be an additive state,  $m(A) = f(\int_{\Omega} \mu_A dP, \int_{\Omega} \nu_A dP)$ .

L. Magdalena, M. Ojeda-Aciego, J.L. Verdegay (eds): Proceedings of IPMU'08, pp. 1675–1677 Torremolinos (Málaga), June 22–27, 2008 Then there are functions

$$\varphi:[0,1]\rightarrow [0,1], \psi:[0,1]\rightarrow [0,1]$$

such that  $\varphi$  is non-decreasing,  $\psi$  is non-increasing,

$$\varphi(1) = \psi(0) = 1, \varphi(0) + \psi(1) = 1,$$

and

$$m(A) = \varphi(\int_{\Omega} \mu_A dP) + \psi(\int_{\Omega} \nu_A dP) - 1.$$

If  $m: \mathcal{F} \to [0,1]$  is an *M*-state, then  $\varphi, \psi$  are continuous.

**Example 1.** Choose  $\alpha \in [0,1]$  and put  $\varphi(x) = (1-\alpha)x + \alpha, \psi(y) = -\alpha y + 1$ . Then

$$m(A) = (1 - \alpha) \int_{\Omega} \mu_A dP + \alpha (1 - \int_{\Omega} \nu_A dP),$$

hence by [4] (see also [6]), any L-state is an M-state.

**Example 2.** Put  $\varphi(x) = \frac{x^2}{2} + \frac{1}{2}, \psi(y) = 1 - \frac{y^2}{2}$ . Then

$$m(A) = \frac{1}{2} (\int_{\Omega} \mu_A^2 dP + 1 - \int_{\Omega} \nu_A^2 dP).$$

The mapping  $m : \mathcal{F} \to [0, 1]$  is an example of an M-state that is not an L-state.

**Proof of Theorem.** First by the formula

$$\bar{m}((\mu_A, \nu_A)) = m((\mu_A, 0)) + m((0, \nu_A)) - m((0, 0))$$

an extension  $\overline{m} : \mathcal{M} \to [0,1]$  can be constructed, where

 $\mathcal{M} = \{(\mu_A, \nu_A); \mu_A, \nu_A : \Omega \to [0, 1], \mu_A, \nu_A \text{ are } \mathcal{S}\text{-measurable } \}.$ 

It is easy to see that  $\overline{m}$  is an additive *M*-probability, and  $\overline{m}$  is continuous, if *m* is continuous. Moreover, if  $(\mu_A, \nu_A) \in \mathcal{F}$ , then

$$(0,0) \lor (\mu_A, \nu_A) = (\mu_A \lor 0, \nu_A \land 0) = (\mu_A, 0),$$

$$(0,0) \land (\mu_A, \nu_A) = (\mu_A \land 0, \nu_A \lor 1) = (0, \nu_A),$$

hence

$$m((0,0)) + m((\mu_A,\nu_A)) = m((\mu_A,0)) + m((0,0))$$

and therefore

$$m((\mu_A, \nu_A)) = m((\mu_A, 0)) + m((0, \nu_A)) -m((0, 0)) = \bar{m}((\mu_A, \nu_A)),$$

 $\overline{m}$  is an extension of m. It is unique, because if s is any extension of m, then again

$$s((\mu_A, \nu_A)) = s((\mu_A, 0)) + s((0, \nu_B))$$
  
-s((0, 0)) = m((\mu\_A, 0)) + m((0, \nu\_A))  
-m((0, 0)) = \bar{m}((\mu\_A, \nu\_A)).

Put now

$$x = \int_{\Omega} \mu_A dP, y = \int_{\Omega} \nu_A dP,$$

hence

$$m(A) = f(x, y).$$

Define

$$\varphi(x) = f(x,0) = m(\int_{\Omega} \mu_A, 0),$$
  
$$\psi(y) = f(1,y) = m(1, \int_{\Omega} \nu_A dP),$$

hence  $\varphi : [0,1] \to [0,1]$  is non-decreasing,  $\psi : [0,1] \to [0,1]$  is non-increasing. Since

$$(\mu_A, 0) \lor (1, \nu_A) = (1, 0), (\mu_A, 0) \land (1, \nu_A) = (\mu_A, \nu_A),$$

we have

$$m(\mu_A, 0) + m(1, \nu_A) = m(\mu_A, \nu_A) + m(1, 0),$$
  

$$f(x, 0) + f(1, y) = f(x, y) + f(1, 0),$$
  

$$\varphi(x) + \psi(y) = f(x, y) + 1,$$
  

$$f(x, y) = \varphi(x) + \psi(y) - 1.$$

We have

$$m(A) = f\left(\int_{\Omega} dP, \int_{\Omega} \nu_A dP\right) =$$
$$= \varphi\left(\int_{\Omega} \mu_A dP\right) + \psi\left(\int_{\Omega} \nu_A dP\right) - 1$$

Since

$$(0,0) \lor (1,1) = (1,0),$$
  
 $(0,1) \land (1,1) = (0,1)$ 

we have

$$f(0,0) + f(1,1) = f(1,0) + f(0,1) = 1,$$
  
$$\varphi(0) + \psi(1) = 1.$$

## Acknowledgements

Supported by Grant VEGA 1/0539/08.

### References

- K. Čunderlíková, B. Riečan. Intuitionistic fuzzy probability theory. In: *Intuitionistic Fuzzy Sets*, Springer, to appear.
- M. Krachounoff (2006). Intuitionistic probability and intuitionistic fuzzy sets.
   In: First Intern. Workshop on IFS (El-Darzi et al. eds.), pages 714-717.
- B. Riečan (2003). A descriptive definition of the probability on intuitionistic fuzzy sets. In: EUSFLAT'2003 (M. Wagenecht, R. Hampel eds.), pages 263-266.
- [4] B. Riečan (2006). On a problem of Radko Mesiar: general form of IF-probabilities. *Fuzzy Sets and Systems*, 152, pages 1485-1490.
- [5] B. Riečan (2005). On the probability on IF-sets and MV-algebras. Notes on IFS, 11, pages 21-25.
- [6] B. Riečan (2007). Probability theory on intuitionistic fuzzy sets. A volume in honor of Daniele Munidici's 60th birthday. Lecture Notes in Computer Science 2007.
- [7] B. Riečan, D. Mundici (2002). Probability on MV-algebras. *Handbook of mea*sure theory (E.Pap ed.), North-Holland 2002.